

In-System Programming Guide

SLG46824/6 ISPG-SLG46824/6

ISPG-SLG46824/6



SLG46824/6

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ISPG-SLG46824/6



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1 Terms and Definitions

ACK Acknowledge Bit
ERSE Erase Enable
ERSR Erase Register
IO Input/Output

LSB Least Significant Bit MSB Most Significant Bit

NPR Non-Volatile Memory Read/Write/Erase Protection

NVM Non-Volatile Memory
PRL Protect Lock Bit
R/W Read/Write

RPR Register Read/Write Protection

SCL I²C Clock Input

SDA I²C Data Input/Output
WPB Write Protect Block Bits
WPR Write Protection Register
WPRE Write Protect Register Enable



2 Introduction

This document describes the in-system programming procedures for SLG46824 and SLG46826.

3 Hardware Requirements

3.1 Pinout and Signals

Four pins are required to program the SLG46824/6: VDD, GND, SCL, and SDA.

The V_{DD} pin requires a voltage ranging from 2.5 V to 5.5 V for Programming (Write) operations, and 2.3 V to 5.5 V for Verification (Read) operations.

The SCL and SDA pins are defined to be standard I²C signaling. I²C Fast Mode Plus speed (1 MHz) NVM read and I²C Fast Mode speed (400 kHz) NVM write communication is supported for these devices. For the timing characteristics for signals on these pins refer to Table 1.

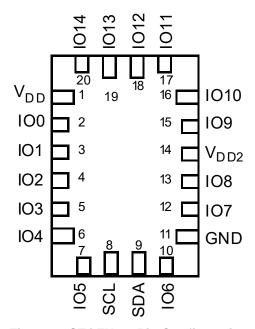


Figure 1: STQFN-20 Pin Configuration

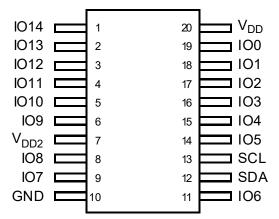


Figure 2: TSSOP-20 Pin Configuration



Table 1: I²C Specifications

			Fa	st-Mo	de	Fast-Mode Plus			
Symbol	Parameter	Condition	Min	Тур	Max	Min	Тур	Max	Unit
F _{SCL}	Clock Frequency, SCL	$V_{DD} = 2.3 \text{ V to } 5.5 \text{ V}$			400			1000	kHz
t_{LOW}	Clock Pulse Width Low	$V_{DD} = 2.3 \text{ V to } 5.5 \text{ V}$	1300			500			ns
thigh	Clock Pulse Width High	$V_{DD} = 2.3 \text{ V to } 5.5 \text{ V}$	600			260			ns
tı	Input Filter Spike Suppression (SCL, SDA)	V _{DD} = 2.3 V to 5.5 V			50			50	ns
taa	Clock Low to Data Out Valid	V _{DD} = 2.3 V to 5.5 V			900			450	ns
t _{BUF}	Bus Free Time between Stop and Start	V _{DD} = 2.3 V to 5.5 V	1300		-	500			ns
thd_sta	Start Hold Time	$V_{DD} = 2.3 \text{ V to } 5.5 \text{ V}$	600			260			ns
tsu_sta	Start Set-up Time	$V_{DD} = 2.3 \text{ V to } 5.5 \text{ V}$	600			260			ns
thd_dat	Data Hold Time	$V_{DD} = 2.3 \text{ V to } 5.5 \text{ V}$	0			0			ns
tsu_dat	Data Set-up Time	$V_{DD} = 2.3 \text{ V to } 5.5 \text{ V}$	100			50			ns
t _R	Inputs Rise Time	$V_{DD} = 2.3 \text{ V to } 5.5 \text{ V}$			300			120	ns
t _F	Inputs Fall Time	$V_{DD} = 2.3 \text{ V to } 5.5 \text{ V}$			300			120	ns
tsu_std	Stop Set-up Time	$V_{DD} = 2.3 \text{ V to } 5.5 \text{ V}$	600			260			ns
tон	Data Out Hold Time	V _{DD} = 2.3 V to 5.5 V	50			50			ns



4 Programming Algorithm for NVM Configuration Register Space

The SLG46824 and SLG46826 programming algorithm for the NVM Configuration space consists of a series of I²C Sequential Write commands, each of which will program one 16 byte page of NVM memory (Note 1).

Data "1" cannot be re-programmed as data "0" without erasure. Each byte can only be programmed one time without erasure.

Note 1 The functionality of the device is based upon the registers. The registers will not be reloaded from the NVM until power is cycled or a reset command is issued.

The SLG46824 and SLG46826 can be programmed either with or without an acknowledge polling routine. The acknowledge polling routine is implemented to optimize time sensitive applications that would prefer not to wait the fixed maximum write cycle time (twR). This method allows the application to know instantly when the NVM write cycle has completed, so a subsequent operation can be started.

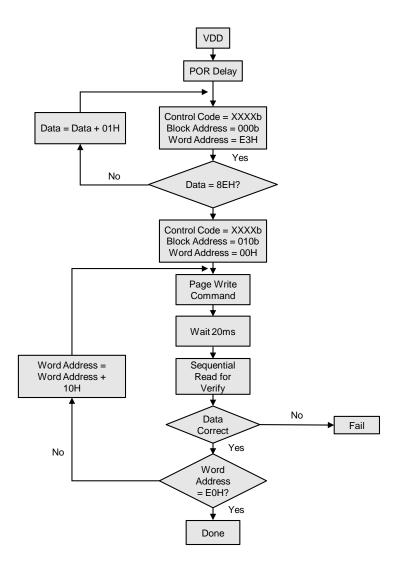


Figure 3: Flowchart for Programming NVM without Acknowledge Polling



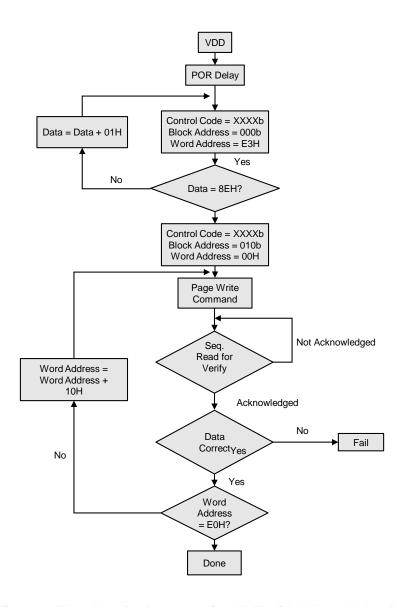


Figure 4: Flowchart for Programming NVM with Acknowledge Polling



5 I²C Signal Specification

5.1 Commands

5.1.1 Write Command

Write access to the NVM is possible by setting A3, A2, A1, A0 to "0000", which allows serial write data for a single page only. Upon receipt of the proper Control Byte and Word Address bytes, the SLG46824/6 will send an ACK. The device will then be ready to receive page data, which is 16 sequential writes of 8-bit data words. The SLG46824/6 will respond with an ACK after each data word is received. The addressing device, such as a Bus Master, must then terminate the write operation with a Stop condition after all page data is written. At that time the GPAK will enter an internally self-timed write cycle, which will be completed within $t_{WR} = 20 \text{ ms}$ (max). While the data is being written into the NVM Memory Array, all inputs, outputs, internal logic, and t_{R}^{2} access to the Register data will be operational/valid.

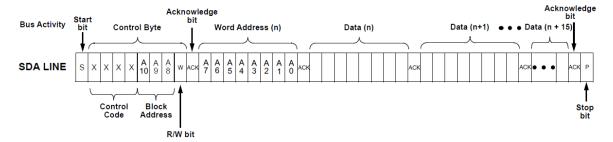


Figure 5: Page Write Command Example

5.1.2 Verify Command

The Random Sequential Read command can be used for verification. The command starts with a Control Byte (with R/W bit set to "0", indicating a write command) and Word Address to set the internal byte address, followed by a Start bit, and then the Control Byte for the read (exactly the same as the Byte Write command). The Start bit in the middle of the command will halt the decoding of a Write command, but will set the internal address counter in preparation for the second half of the command. After the Start bit, the Bus Master issues a second Control Byte with the R/W bit set to "1", after which the SLG46824/6 issues an Acknowledge bit, followed by the requested eight data bits. Once the SLG46824/6 transmits the first data byte, the Bus Master issues an Acknowledge bit. The Bus Master can continue reading sequential bytes of data, and will terminate the command with a Stop condition.

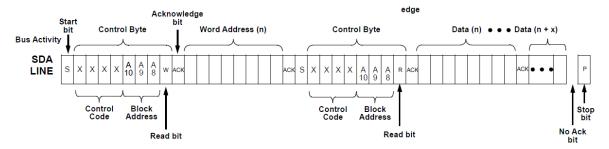


Figure 6: Random Sequential Read Command

5.1.3 Erase Command

The erase scheme allows a 16 byte page in the emulated EEPROM (Note 2) space or the 2K bits NVM chip configuration space to be erased by modifying the contents of the Erase Register (ERSR). When the ERSE bit is set in the ERSR register, the device will start a self-timed erase cycle which will complete in a maximum of $t_{\rm ER} = 20$ ms (max). Changing the state of the ERSR is accomplished with a Byte Write sequence with the requirements outlined in this section. The ERSR register is located on the E3H address.



Note 2 Emulated EEPROM is available for SLG46826 only.

Table 2: Erase Register Bit Format

	b7	b6	b5	b4	b3	b2	b1	b0
Page Erase Register	ERSE			ERSEB4	ERSEB3	ERSEB2	ERSEB1	ERSEB0

Table 3: Erase Register Bit Function Description

Bit	Name		Туре	Description
7	ERSE	Erase Enable	W	Setting b7 bit to "1" will start in internal erase cycle on the page defined by ERSEB4-0
6				
5				
4	ERSEB4		W	
3	ERSEB3	Page	W	Define the page address, which will be erased. ERSB4 = 0 corresponds to the Upper 2K NVM used for chip
2	ERSEB2	Selection	W	configuration;
1	ERSEB1	for Erase	W	ERSB4 = 1 corresponds to the 2-k emulated EEPROM (Note 2)
0	ERSEB0		W	

Upon receipt of the proper Device Address and Erase Register Address, the SLG46824/6 will send an ACK. The device will then be ready to receive Erase Register data. The SLG46824/6 will respond with a non-compliant I^2C ACK after the Erase Register data word is received. Please reference the SLG46824/6 errata document (revision XC) posted on Dialog's website for more information. The addressing device, such as a Bus Master, must then terminate the write operation with a Stop condition. At that time, the GPAK will enter an internally self-timed erase cycle, which will be completed within t_{ER} (max 20 ms). While the data is being written into the Memory Array, all inputs, outputs, internal logic, and I^2C access to the Register data will be operational/valid.

After the erase has taken place, the contents of ERSE bits will be set to "0" automatically. Erase will be triggered by Stop Bit in I²C command.

5.2 Addressing

Each command to the I²C Serial Communications macrocell begins with a Control Byte. The bits inside this Control Byte are shown in Figure 7. After the Start bit, the first four bits are a control code. Each bit in the control code can be sourced independently from the register or by value defined externally by IO5, IO4, IO3, and IO2. The LSB of the control code is defined by the value of IO2, while the MSB is defined by the value of IO5. The address source (either register bit or PIN) for each bit in the control code is defined by registers [1623:1620]. This gives the User flexibility on the chip level addressing of this device and other devices on the same I²C bus. **The default control code is 0001.** The Block Address is the next three bits (A10, A9, A8), which will define the most significant bits in the addressing of the data to be read or written by the command. The last bit in the Control Byte is the R/W bit, which selects whether a read command or write command is requested, with a "1" selecting for a Read command, and a "0" selecting for a Write command. This Control Byte will be followed by an Acknowledge bit (ACK), which is sent by this device to indicate successful communication of the Control Byte data.



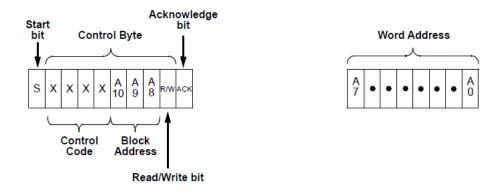


Figure 7: Page Write Command



6 Memory Space

6.1 Memory Map

In the read and write command address structure there are a total of 11 bits of addressing, each pointing to a unique byte of information, resulting in a total address space of 16K bytes. Valid addresses are shown in the memory map in Figure 8.

Lowest I ² C	I ² C E	Block Addı	ess	Memory Space	
Address = 000h	A10 = 0	A9 = 0	A8 = 0	2 Kbits Register Data Configuration	
	A10 = 0	A9 = 0	A8 = 1	Not Used	
	A10 = 0	A9 = 1	A8 = 0	2 Kbits NVM Data Configuration	16 pages to configure GPAK
	A10 = 0	A9 = 1	A8 = 1	2 Kbits EEPROM (Note 2)	16 pages for emulated EEPROM
Highest I ² C Address = 7FFh	A10 = 1	A9 = X	A8 = X	Not Used	(Note 2)

Figure 8: I²C Block Addressing

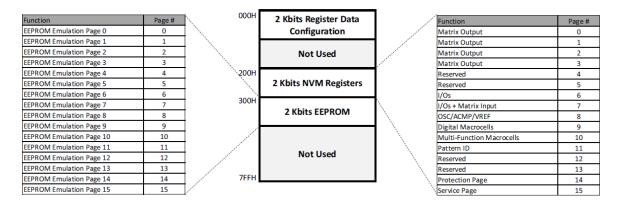


Figure 9: I²C Address Mapping

6.2 Special Pages

GreenPAK's internal NVM memory is divided into 32 pages which hold 16 bytes each. 16 pages are used to configure the GreenPAK, and the other 16 are used for the emulated EEPROM (Note 2) function.

6.2.1 Protection Page

Page #14 inside the 2Kbits NVM Registers memory space is a dedicated protection page. All 16 bytes of Page #14 are dedicated to protection settings, even though only 3 of those bytes are used. The



whole page is used because a page is the smallest NVM section that can be programmed/erased or blocked for erase/program.

Once the User determines the security setting, they can do an NVM page 14 programming (program the security setting and set security page lock bit = 1). The changes to the Protection Page will not be active until the device is reset. The user can do an immediate reset using one of the following methods:

- Power down the device, then power it back on
- Perform a soft reset using an I²C command

This will allow the memory interface circuit to know that page 14 (security page) is write/erase protected.

6.2.2 Service Page

Page #15 inside the 2Kbits NVM Registers memory space contains reserved information that is preprogrammed during device final test. The information on this page can be Read but not Written by the User. As this page cannot be altered by the User, the programming algorithm does not need to address this page.



7 Programming Algorithm for the Emulated EEPROM Space

The SLG46824 and SLG46826 programming algorithm for the emulated EEPROM (Note 2) space consists of a series of I²C Sequential Write commands, each of which will program one 16 byte page of NVM memory.

Data "1" cannot be re-programmed as data "0" without erasure. Each byte can only be programmed one time without erasure.

Programming of the emulated EEPROM (Note 2) follows a similar flow to programming of the NVM with two differences:

- Block Address for emulated EEPROM (Note 2) is 011b (in contrast to the NVM Configuration Registers Block Address, which is 010b)
- With emulated EEPROM (Note 2), all 16 pages are user accessible.

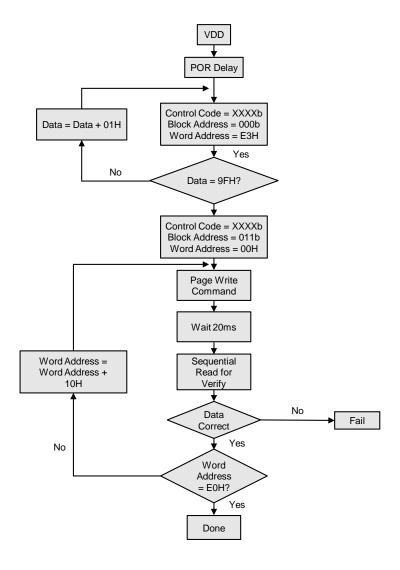


Figure 10: Flowchart for Programming EEPROM without Acknowledge Polling



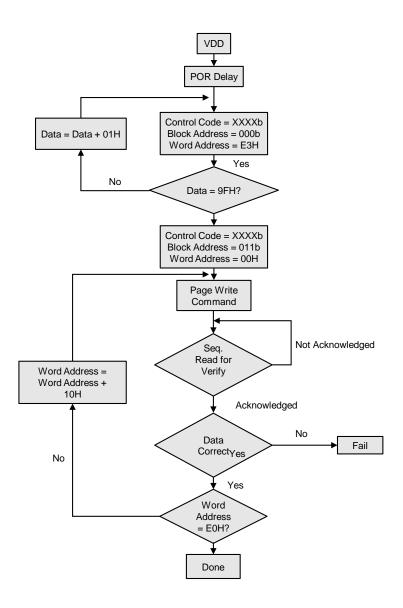


Figure 11: Flowchart for Programming Emulated EEPROM with Acknowledge Polling



8 Protection for Emulated EEPROM

The SLG46824/6 utilizes a software scheme that allows a portion or the entire emulated EEPROM (Note 2) to be inhibited from being written/ erased to by modifying the contents of the Write Protection Register (WPR). If desired, the WPR can be set so that it may no longer be modified/erased, thereby making the current protection scheme permanent. The status of the WPR can be determined by following a Random Read sequence. Changing the state of the WPR is accomplished with a Byte Write sequence with the requirements outlined in this section.

The WPR register is located on I²C Block Address = 000b, I²C Word Address = E2H.The WPR format is shown in Table 4, and the WPR bit functions are included in Table 5.

Table 4: Write/Erase Protect Register Format

	b7	b6	b5	b4	b3	b2	b1	b0
WPR						WPRE	WPB1	WPB0

Table 5: Write/Erase Protect Register Bit Function Description

Bit	Name		Туре	Description
2	WPRE	Write Protect Register Enable	R/W	O: No Software Write Protection enabled (default) 1: Write Protection is set by the state of WPB[1:0] bits
	WPB1	Write	R/W	00: Upper quarter of emulated EEPROM (Note 2) is write protected (default)
1:0	WPB0	Protect Block Bits	R/W	01: Upper half of emulated EEPROM (Note 2) is write protected 10: Upper 3/4 of emulated EEPROM (Note 2) is write protected 11: Entire emulated EEPROM (Note 2) is write protected

Write Protect Enable (WPRE): The Write Protect Enable Bit is used to enable or disable the device Software Write/Erase Protect. A Logic 0 in this position will disable Software Write/Erase Protection, and a Logic 1 will enable this function.

Write Protect Block Bits (WPB1:WPB0): The Write Protect Block bits allow four levels of protection of the Memory Array, provided that the WPRE bit is a Logic 1. If the WPRE bit is a Logic 0, the state of the WPB1:0 bits have no impact on device protection.

Protect Lock Bit (PRL): The Protect Lock Bit is used to permanently lock the current state of the WPR, as well as RPR and NPR. A Logic 0 indicates that the WPR, RPR, and NPR can be modified, whereas a Logic 1 indicates the WPR, RPR, and NPR has been locked and can no longer be modified. The PRL register bit is located at register [1824].



Revision History

Revision	Date	Description
1.2	14-Sep-2020	Updated according to Dialog's Writing Guideline
1.1	4-Mar-2019	Updated Flowcharts Added a reference to the NVM and EEPROM Erase Register erratum in section 3.1.3
1.0	13-Feb-2018	Initial release



Status Definitions

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